

## Chapter 13. VECTORS IN THREE DIMENSIONAL SPACE

Let's begin with some names and notation for things:

$\mathbb{R}$  is the set (collection) of real numbers. We write  $x \in \mathbb{R}$  to mean that  $x$  is a real number. A real number is also called a **scalar** because it can be used to scale vectors.

$\mathbb{R}^2$  is the usual  $xy$ -plane. More precisely,  $\mathbb{R}^2$  is the set of vectors  $\mathbf{u} = (x, y)$ , with  $x, y \in \mathbb{R}$ . We have studied vectors in  $\mathbb{R}^2$  in the previous chapters.

$\mathbb{R}^3$  is three dimensional  $xyz$  space. More precisely,  $\mathbb{R}^3$  is the set of vectors  $\mathbf{u} = (x, y, z)$  with  $x, y, z \in \mathbb{R}$ . In this chapter we concentrate on vectors in  $\mathbb{R}^3$ .

There are four vectors in  $\mathbb{R}^3$  having special notation:

$$\mathbf{e}_1 = (1, 0, 0), \quad \mathbf{e}_2 = (0, 1, 0), \quad \mathbf{e}_3 = (0, 0, 1), \quad \mathbf{0} = (0, 0, 0).$$

The vectors  $\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3$  are called the **standard basis vectors** and the vector  $\mathbf{0}$  is called the **zero vector**.

### Vectors as arrows

Any two points in space determine a vector that measures the difference between the points. If  $P = (a, b, c)$  and  $P' = (a', b', c')$  are two points in  $\mathbb{R}^3$  then the vector  $\mathbf{u}$  from  $P$  to  $P'$  is

$$\mathbf{u} = (a' - a, b' - b, c' - c).$$

You can visualize  $\mathbf{u}$  as an arrow drawn from  $P$  to  $P'$ . If you move this arrow, without changing its length or direction, so that the base of the arrow is at  $(0, 0, 0)$ , then the tip of the arrow will be at  $(a - a', b - b', c - c')$ .

### Adding vectors

We can do arithmetic with vectors. We'll start with vector addition and related operations. Suppose you have two vectors

$$\mathbf{u} = (x, y, z), \quad \mathbf{v} = (x', y', z').$$

Then you can add these two vectors:

$$\mathbf{u} + \mathbf{v} = (x + x', y + y', z + z'),$$

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subtract them:

$$\mathbf{u} - \mathbf{v} = (x - x', y - y', z - z'),$$

and multiply one of them by a scalar  $c \in \mathbb{R}$ :

$$c\mathbf{u} = (cx, cy, cz).$$

If you combine these operations with several vectors  $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_n$  and scalars  $c_1, c_2, \dots, c_n$ , then you get what is called a **linear combination** of the vectors  $\mathbf{u}_i$ :

$$c_1\mathbf{u}_1 + c_2\mathbf{u}_2 + \dots + c_n\mathbf{u}_n.$$

Every vector in  $\mathbb{R}^3$  is a linear combination of the standard basis vectors

$$\mathbf{e}_1 = (1, 0, 0), \quad \mathbf{e}_2 = (0, 1, 0), \quad \mathbf{e}_3 = (0, 0, 1).$$

Namely, if  $\mathbf{u} = (x, y, z)$  then

$$\mathbf{u} = x\mathbf{e}_1 + y\mathbf{e}_2 + z\mathbf{e}_3.$$

If we have two non-proportional vectors  $\mathbf{u}$  and  $\mathbf{v}$ , the collection of all their linear combinations  $c_1\mathbf{u} + c_2\mathbf{v}$  forms a plane, called the **span** of  $\mathbf{u}$  and  $\mathbf{v}$ . If we take only those linear combinations where  $0 \leq c_i \leq 1$  for both  $i = 1$  and  $i = 2$ , we get the **parallelogram** spanned by  $\mathbf{u}$  and  $\mathbf{v}$

## THE DOT PRODUCT

There are two different ways to multiply vectors in  $\mathbb{R}^3$ . For the first way, take two vectors

$$\mathbf{u} = (x, y, z), \quad \mathbf{v} = (x', y', z').$$

Their **dot product** is defined by

$$\langle \mathbf{u}, \mathbf{v} \rangle = xx' + yy' + zz'. \quad (1)$$

(In other books, this is sometimes written  $\mathbf{u} \cdot \mathbf{v}$ , hence the name “dot”. The notation  $\langle \mathbf{u}, \mathbf{v} \rangle$  will be more convenient for later calculations.)

The dot product is **symmetric**, meaning that

$$\langle \mathbf{u}, \mathbf{v} \rangle = \langle \mathbf{v}, \mathbf{u} \rangle,$$

and **bilinear**, meaning that if you have three vectors  $\mathbf{u}, \mathbf{v}, \mathbf{w}$  and scalars  $a, b$ , then

$$\langle a\mathbf{u} + b\mathbf{v}, \mathbf{w} \rangle = a\langle \mathbf{u}, \mathbf{w} \rangle + b\langle \mathbf{v}, \mathbf{w} \rangle.$$

If you think of the vector  $\mathbf{u} = (x, y, z)$  as an arrow, then the **length**  $|\mathbf{u}|$  of  $\mathbf{u}$  is given by

$$|\mathbf{u}| = \sqrt{\langle \mathbf{u}, \mathbf{u} \rangle} = \sqrt{x^2 + y^2 + z^2}.$$

The vector  $\mathbf{u}$  is called a **unit vector** if  $|\mathbf{u}| = 1$ . This means that  $\mathbf{u}$  lies on the unit sphere centered at  $\mathbf{0}$  in  $\mathbb{R}^3$ .

If  $\mathbf{u}$  is any nonzero vector, then we can scale it

$$\frac{1}{|\mathbf{u}|} \mathbf{u}$$

to get a unit vector in the same direction.

Geometrically, the dot product of  $\mathbf{u}$  and  $\mathbf{v}$  is the product of their lengths times the cosine of the angle  $\theta$  between them. That is,

$$\langle \mathbf{u}, \mathbf{v} \rangle = |\mathbf{u}| |\mathbf{v}| \cos \theta. \quad (2)$$

To see this, apply the Law of Cosines to the triangle with vertices  $\mathbf{0}$ ,  $\mathbf{u}$ ,  $\mathbf{v}$ . We find that

$$|\mathbf{u} - \mathbf{v}|^2 = |\mathbf{u}|^2 + |\mathbf{v}|^2 - 2|\mathbf{u}| |\mathbf{v}| \cos(\theta).$$

Writing the lengths in terms of dot products via equation (1), this says

$$\langle \mathbf{u} - \mathbf{v}, \mathbf{u} - \mathbf{v} \rangle = \langle \mathbf{u}, \mathbf{u} \rangle + \langle \mathbf{v}, \mathbf{v} \rangle - 2|\mathbf{u}| |\mathbf{v}| \cos \theta.$$

Using symmetry and bilinearity, this equation becomes

$$\langle \mathbf{u}, \mathbf{u} \rangle - 2\langle \mathbf{u}, \mathbf{v} \rangle + \langle \mathbf{v}, \mathbf{v} \rangle = \langle \mathbf{u}, \mathbf{u} \rangle + \langle \mathbf{v}, \mathbf{v} \rangle - 2|\mathbf{u}| |\mathbf{v}| \cos \theta,$$

and if we simplify this, we get equation (2).

### Computations with the dot product:

(i) *The angle between two vectors.*

For example, the vectors  $\mathbf{u}$  and  $\mathbf{v}$  are **perpendicular** (also called **orthogonal**) exactly when

$$\langle \mathbf{u}, \mathbf{v} \rangle = 0.$$

This is because  $\cos \theta = 0$  exactly when  $\theta$  is an odd multiple of  $\pi/2$ .

More generally, you can use equations (1) and (2) to find the angle between any two vectors. For example, suppose we have the vectors

$$\mathbf{u} = (1, 2, 3), \quad \mathbf{v} = (3, 2, 1),$$

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then using (1) we get

$$\langle \mathbf{u}, \mathbf{v} \rangle = 3 + 4 + 3 = 10.$$

Then using (2) we get

$$10 = \langle \mathbf{u}, \mathbf{v} \rangle = \sqrt{14}\sqrt{14} \cos \theta,$$

so

$$\cos \theta = \frac{10}{14} = \frac{5}{7}.$$

(ii) *The projection of a vector onto a line.*

Note that if  $\mathbf{u}$  and  $\mathbf{v}$  are unit vectors, then (2) simplifies:

$$\langle \mathbf{u}, \mathbf{v} \rangle = \cos \theta, \quad \text{if } |\mathbf{u}| = |\mathbf{v}| = 1.$$

If just one of them, say  $\mathbf{u}$ , is a unit vector, then

$$\langle \mathbf{u}, \mathbf{v} \rangle = \text{length of projection of } \mathbf{v} \text{ onto the line through } \mathbf{u}.$$

(iii) *The equation of a plane.*

Given a plane through a point  $P_0 = (x_0, y_0, z_0)$ , and a vector  $\mathbf{n} = (a, b, c)$  perpendicular to the plane, the plane has equation

$$a(x - x_0) + b(y - y_0) + c(z - z_0) = 0. \quad (3)$$

This is because a general point  $P = (x, y, z)$  lies on the plane exactly when the vector  $\mathbf{u}$  from  $P_0$  to  $P$  is perpendicular to  $\mathbf{n}$ . This happens exactly when  $\langle \mathbf{n}, \mathbf{u} \rangle = 0$ , which is equation (3). The vector  $\mathbf{n}$  is called the **normal vector** of the plane.

(iv) *Orthonormal Bases.*

Suppose we have three vectors  $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$ . We say these vectors form an **orthonormal basis** of  $\mathbb{R}^3$  if

$$\langle \mathbf{u}_i, \mathbf{u}_j \rangle = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j. \end{cases}$$

To see lots of orthonormal bases, take a cube with side length one, and put one corner at  $\mathbf{0}$ . The three edges coming out of this corner are an orthonormal basis.

For example, the standard basis  $\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3$  is orthonormal. Taken in this order, the standard basis is right handed, in the sense that if you bend your right hand to a right angle, such that the first vector (in this case  $\mathbf{e}_1$ ) points along your fingers toward the tips, and the second vector (in this case  $\mathbf{e}_2$ ) points along your palm toward the wrist, then your thumb will point in the direction of the third vector (in this case  $\mathbf{e}_3$ ). On the other hand (!) the orthonormal basis  $\mathbf{e}_1, \mathbf{e}_2, -\mathbf{e}_3$  is left handed. Every orthonormal basis is either left-handed or right-handed. The right-handed ones are obtained by simultaneously rotating  $\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3$ , and the left handed ones by simultaneously rotating  $\mathbf{e}_1, \mathbf{e}_2, -\mathbf{e}_3$ .

### THE CROSS PRODUCT IN $\mathbb{R}^3$

The second way of multiplying vectors in  $\mathbb{R}^3$  gives you another vector. Take two vectors

$$\mathbf{u} = (x, y, z), \quad \mathbf{v} = (x', y', z').$$

Their cross product is the vector

$$\mathbf{u} \times \mathbf{v} = (yz' - zy', zx' - xz', xy' - yx'). \quad (4)$$

One way to remember this is via the  $2 \times 3$  matrix

$$\begin{bmatrix} x & y & z \\ x' & y' & z' \end{bmatrix}.$$

Let  $A_i$  be the  $2 \times 2$  submatrix obtained by removing the  $i^{\text{th}}$  column:

$$A_1 = \begin{bmatrix} y & z \\ y' & z' \end{bmatrix}, \quad A_2 = \begin{bmatrix} x & z \\ x' & z' \end{bmatrix}, \quad A_3 = \begin{bmatrix} x & y \\ x' & y' \end{bmatrix}.$$

Then

$$\mathbf{u} \times \mathbf{v} = (\det A_1, -\det A_2, \det A_3).$$

### Basic properties of cross-product:

1. (Bilinearity) If you have three vectors  $\mathbf{u}, \mathbf{v}, \mathbf{w}$  and scalars  $a, b$ , then

$$(a\mathbf{u} + b\mathbf{v}) \times \mathbf{w} = a(\mathbf{u} \times \mathbf{w}) + b(\mathbf{v} \times \mathbf{w}).$$

## 2. (Antisymmetry)

$$\mathbf{u} \times \mathbf{v} = -\mathbf{v} \times \mathbf{u}.$$

In particular, we have

$$\mathbf{u} \times \mathbf{u} = \mathbf{0}.$$

In fact, we have  $\mathbf{u} \times \mathbf{v} = \mathbf{0}$  exactly when  $\mathbf{u}$  and  $\mathbf{v}$  are proportional.

3.  $\mathbf{u} \times \mathbf{v}$  is orthogonal to both  $\mathbf{u}$  and  $\mathbf{v}$ .
4.  $\mathbf{u} \times \mathbf{v}$  points in the direction of your right thumb when  $\mathbf{u}$  points along your fingers and  $\mathbf{v}$  points along your palm toward the wrist.
5. The length of  $|\mathbf{u} \times \mathbf{v}|$  is given by

$$|\mathbf{u} \times \mathbf{v}| = |\mathbf{u}||\mathbf{v}| \sin \theta, \quad (5)$$

where  $\theta$  is the acute angle (between 0 and  $\pi$ ) between  $\mathbf{u}$  and  $\mathbf{v}$ .

You will verify some of these properties in the exercises below.

### Computations with the cross-product:

#### (i) Area of a triangle in space.

Equation means that  $|\mathbf{u} \times \mathbf{v}|$  is the area of the parallelogram spanned by  $\mathbf{u}$  and  $\mathbf{v}$ . Hence the triangle with edges  $\mathbf{u}$ ,  $\mathbf{v}$ ,  $\mathbf{v} - \mathbf{u}$  has area  $\frac{1}{2}|\mathbf{u} \times \mathbf{v}|$ .

Here's another way to think of this area: Take a triangle  $\Delta$  in space and let  $\mathbf{u}$ ,  $\mathbf{v}$ ,  $\mathbf{w}$  be the vertices of  $\Delta$ . If you think of  $\mathbf{u}$ ,  $\mathbf{v}$ ,  $\mathbf{w}$  as arrows based at  $\mathbf{0}$ , then  $\Delta$  is formed by the tips of these arrows.

Two of the sides of  $\Delta$  are the vectors  $\mathbf{v} - \mathbf{u}$  and  $\mathbf{w} - \mathbf{u}$ . So the area of  $\Delta$  is

$$\text{Area}(\Delta) = \frac{1}{2}|(\mathbf{v} - \mathbf{u}) \times (\mathbf{w} - \mathbf{u})|.$$

Using bilinearity of the cross product, we get

$$(\mathbf{v} - \mathbf{u}) \times (\mathbf{w} - \mathbf{u}) = \mathbf{v} \times \mathbf{w} - \mathbf{u} \times \mathbf{w} - \mathbf{v} \times \mathbf{u} + \mathbf{u} \times \mathbf{u}.$$

By antisymmetry, we have  $\mathbf{u} \times \mathbf{u} = \mathbf{0}$ , and

$$(\mathbf{v} - \mathbf{u}) \times (\mathbf{w} - \mathbf{u}) = \mathbf{v} \times \mathbf{w} + \mathbf{w} \times \mathbf{u} + \mathbf{u} \times \mathbf{v}.$$

So we get the formula for the area of a triangle  $\Delta$  with vertices  $\mathbf{u}$ ,  $\mathbf{v}$ ,  $\mathbf{w}$ :

$$\text{Area}(\Delta) = \frac{1}{2} |\mathbf{u} \times \mathbf{v} + \mathbf{v} \times \mathbf{w} + \mathbf{w} \times \mathbf{u}|. \quad (6)$$

Note the cyclic pattern. You will use equation (6) to prove the three dimensional Pythagorean theorem in Exercise 13.7 below.

(ii) *Equation of the plane spanned by two vectors.*

Recall that two nonproportional vectors  $\mathbf{u}$  and  $\mathbf{v}$  span a plane through the origin. The vectors on this plane are all the linear combinations  $c_1\mathbf{u} + c_2\mathbf{v}$ . Since  $\mathbf{u} \times \mathbf{v}$  is perpendicular to  $\mathbf{u}$  and  $\mathbf{v}$ , it is also perpendicular to each linear combination  $c_1\mathbf{u} + c_2\mathbf{v}$ . Hence  $\mathbf{u} \times \mathbf{v}$  is normal to the plane. Let's say that  $\mathbf{u} \times \mathbf{v} = (a, b, c)$ . Then the equation of the plane spanned by  $\mathbf{u}$  and  $\mathbf{v}$  is

$$ax + by + cz = 0.$$

(iii) *Intersection of two planes.*

Take two distinct planes through the origin. Say they have equations

$$ax + by + cz = 0, \quad a'x + b'y + c'z = 0.$$

Their normal vectors are

$$\mathbf{n} = (a, b, c) \quad \text{and} \quad \mathbf{n}' = (a', b', c'),$$

respectively. Since the planes are distinct, these vectors are nonproportional. The vector  $\mathbf{n} \times \mathbf{n}'$  is nonzero and perpendicular to both  $\mathbf{n}$  and  $\mathbf{n}'$ , so it lies on both planes. The line of intersection of the planes is therefore the line through  $\mathbf{n} \times \mathbf{n}'$ .

**Exercise 13.1** Let  $\mathbf{u} = (x, y, z)$ ,  $\mathbf{v} = (x', y', z')$ . Use the dot product to verify that  $\langle \mathbf{u}, \mathbf{u} \times \mathbf{v} \rangle = 0$ .

**Exercise 13.2** Let  $\mathbf{u} = (1, -2, 1)$ ,  $\mathbf{v} = (2, 1, 1)$ . Find  $\langle \mathbf{u}, \mathbf{v} \rangle$  and  $\mathbf{u} \times \mathbf{v}$  and the angle between  $\mathbf{u}$  and  $\mathbf{v}$ .

**Exercise 13.3** Find a nonzero vector on the line of intersection of the two planes

$$x - 2y + z = 0, \quad 2x + y + z = 0.$$

**Exercise 13.4** Find the angle between the diagonal of a cube and one of the edges of the cube. It doesn't matter which cube you use, but you may wish to use the cube whose vertices are the eight points  $(x, y, z)$  with  $x, y, z$  either 0 or 1.

**Exercise 13.5** Take two vectors

$$\mathbf{u} = (x, y, z) \quad \text{and} \quad \mathbf{v} = (x', y', z').$$

Since  $\mathbf{u} \times \mathbf{v}$  is a vector, its length  $|\mathbf{u} \times \mathbf{v}|$  is a number. The dot product  $\langle \mathbf{u}, \mathbf{v} \rangle$  is also a number. The relation between these numbers is:

$$\langle \mathbf{u}, \mathbf{v} \rangle^2 + |\mathbf{u} \times \mathbf{v}|^2 = |\mathbf{u}|^2 |\mathbf{v}|^2. \quad (7)$$

Prove equation (7) by expanding both sides in terms of  $x, y, z, x', y', z'$ .

**Exercise 13.6** Use Equations (2) and (7) to prove the length formula

$$|\mathbf{u} \times \mathbf{v}| = |\mathbf{u}| |\mathbf{v}| \sin \theta.$$

**Exercise 13.7** Consider the tetrahedron with vertices

$$A = (a, 0, 0), \quad B = (0, b, 0), \quad C = (0, 0, c), \quad \text{and} \quad O = (0, 0, 0).$$

For any three points  $X, Y, Z$  in space, write  $[XYZ]$  for the area of the triangle with vertices  $X, Y, Z$ . Use Equation (6) to prove that

$$[ABC]^2 = [OAB]^2 + [OBC]^2 + [OCA]^2.$$

This is the **three dimensional Pythagorean theorem**.